OOP for Scientific Computing First Exam

points:

| 1	2	3	4	5	Σ
15	20	10	10	10	65

Following was asked in the exam:

1. Explain following aspects of C++ :

   a. `class` vs `struct`?
   b. `namespace`. What is it, when & why is it used?
   c. `private` vs `protected`?
   d. copy elision?
   e. header guards. What, why?
   f. rule of five vs fule of zero?
   g. temporaries? literals?
   h. how does a shared pointer work?
   i. SFINAE?
   j. SOLID?

2. Short code snippets were given and asked to explain & extend. With following topics:

   a. default function args
   b. concepts
   c. template parameters, default template parameters
   d. Constructor, copy constructor, copy assignment operator, move constructor, move assignment operator, overloaded constructor.
   e. Lambda expression, functional programming
   f. Compile time branching
   g. CRTP
   h. Inheritence. How to improve the given implementation

3. Horner Schema: Variadic templates, recursion with templates(?), template metaprogramming

4. An incomplete implementation of an OOP system was given that was supposed to implement a simulation a prey-predator dynamic system, modeled by the Lotka-Volterra differential equations:

$$\frac{dx}{dt} = \alpha x - \beta xy,$$
$$\frac{dy}{dt} = \gamma y - \delta xy$$

The incomplete OOP system had the following basic structure:
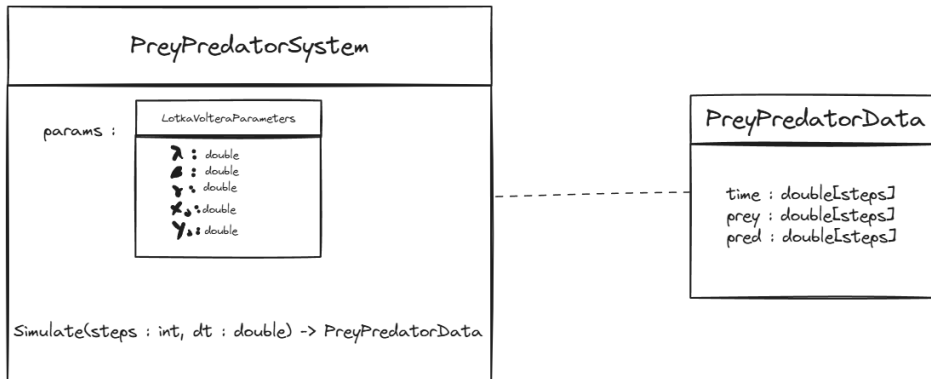
the method "Simulate()" returns an object of type "PreyPredatorData",
and is supposed to populate its members with the simulation data based on discrete
Lotka-Volterra equations.

in a) we were supposed to write an implementation for this method.

Figure 1: Lotka-Volterra OOP System

a) Implement the `PreyPredatorData Simulate(int steps, double dt)` that cre-
ates a `PreyPredatorData` object, populates its members with the simulation data
based on the Lotka-Volterra difference equations and returns the object:

$$X_{n+1} = X_n + \Delta t(\alpha x_n - \beta x_n y_n)$$
$$Y_{n+1} = Y_n + \Delta t(\delta x_n y_n - \gamma y_n)$$

b) ?

5. ?